

# Customized 3d Imaging!

## Collision Avoidance Cone Beam Ct For Interventional Radiology

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### What and Why

#### CBCT facilitates intraoperative 3D imaging

- Better access, lower radiation and cost compared to the clinical CT.

#### Typically, circular trajectory required, but:

- Circular trajectories not always physically possible due to collisions with patients or equipment.
- 3D imaging option not possible and 2D images the only solution.
- Can lead to wrong decisions during the surgery (e.g., wrong placement of the screw in spinal surgery due to lack of 3D view which can paralyze the patient ) or subsequent surgery required.

#### Solution: Enable case specific non-circular trajectories

### Solution and Results

#### Algorithmic solution to physical problem => Software

- An algorithm to design collision-free, patient-specific trajectories was proposed for cases where circular CBCT is not feasible. It personalizes 3D source-detector trajectories (combination of multiple small arcs) to enhance image at target regions of interest. Kinematic constraints are taken into account on-the-fly. Similar imaging performance as the circular trajectory was achieved.

#### CBCT under kinematic constraints comes to the reality for the first time!

- **USP:** paves the way for the next generation, patient-specific collision avoidance 3D CBCT imaging, no hardware modification required, suitable to be implemented on all commercial CBCT devices
- Collaboration between ACMIT, Medical University of Vienna and Wiener Neustadt hospital

### Product Potential > all commercial CBCT devices

#### First verification performed

- Allura FD20 (Philips) C-arm at Landeskrankenhaus Wiener Neustadt (Fig. 2 a)

#### Knowledge transfer through ACMIT network

- In particular to Lower Austria (e.g, MedAustron) and Austrian institution (ImagingRing, medPhoton, Fig. 2 b)

#### Other candidates for novel trajectories

- Artis Zeego (Siemens) (Fig. 2 c) or Loop-X (Brainlab) (Fig. 2 d)
- **SDG:** The software addresses the SDG 'Good health and well-being' with focus on improving surgery output

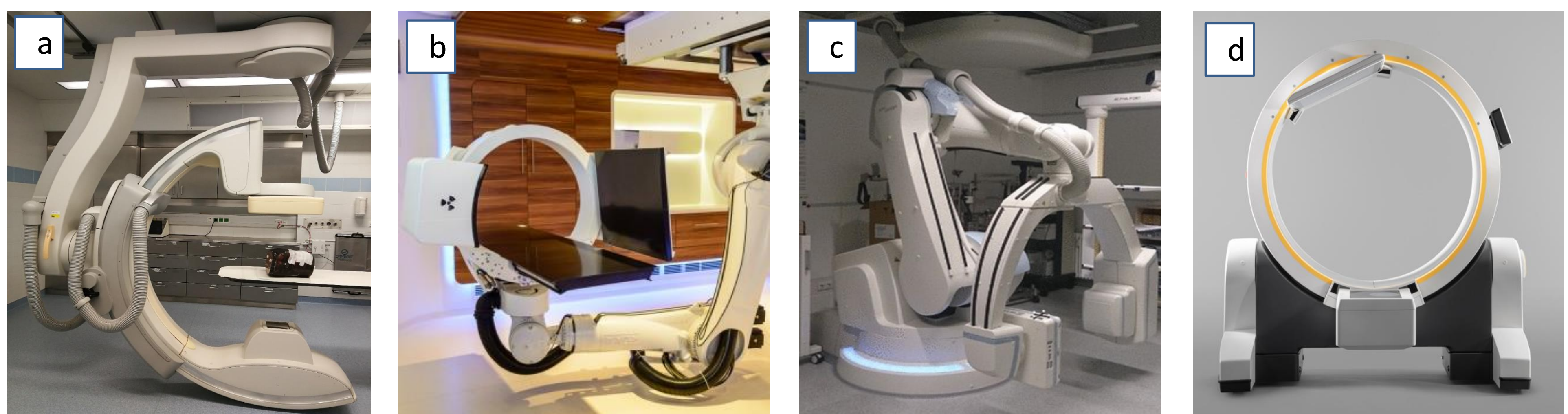


Figure 2. Different advanced CBCT systems which are candidates for implementations of customized trajectories.

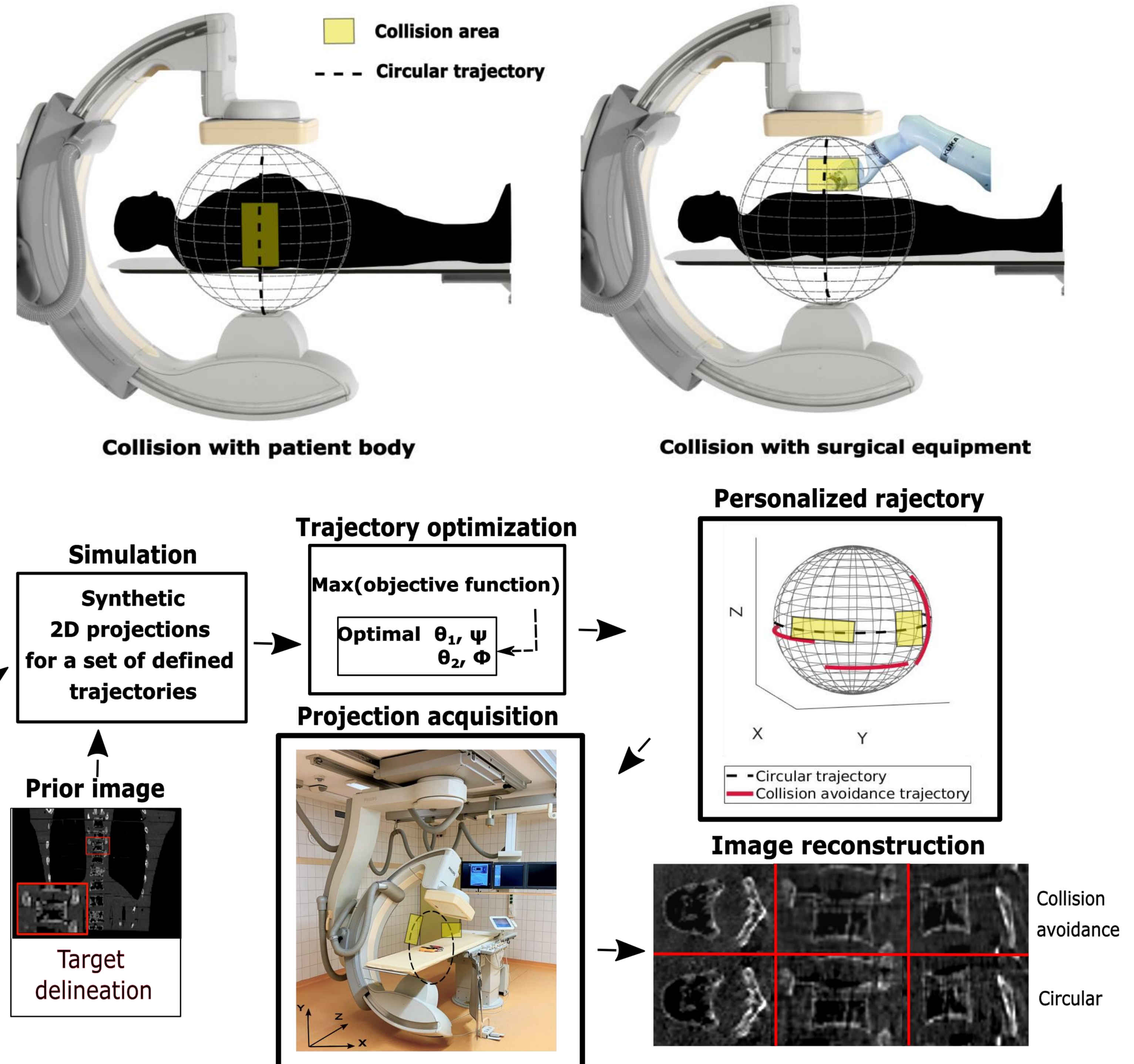


Figure 1. Collision avoidance trajectory optimization framework

### Way to Market

#### Steps required for market-ready solution:

- Further acceleration by means of multiple GPUs parallelization
- Adaptation with different interfaces of different imaging devices
- Automatic execution of novel trajectories to be discussed with providers of imaging technology
- Adaption with different types of sensor input to sense the collisions
- Creation of a comprehensive business model (B2B)
- Software-development process based on certified ISO 13485 quality management system in ACMIT and later EN 62304 for implementation
- ACMIT belongs the IP and predicts a 2-3 years time-line for a market-ready solution, ACMIT will license the IP to different imaging companies

### Potential Clinical and Social Benefit

- Main clinical benefit for obese patients and for interventions where collisions can be avoided
- Enormous clinical applications e.g, pedicle screw insertions, percutaneous needle placement, angiography and many more would benefit
- A strong driver for a more extensive utilization of CBCT imaging with a very positive impact to all stakeholders along the treatment chain

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